

## Assignment-set 2 Introduction to Dynamical Systems 2013

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Deadline to hand in: 31 October 2013, 11.15u

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- 1.) (a) Show that  $\bar{x} = 0$  is an asymptotically stable solution of  $\dot{x} = -x^3$  ( $\in \mathbf{R}$ ). Use the definition! (see page 118 of the book).
- (b) Is this also true for the *complex* equation  $\dot{z} = -z^3$  (with  $z \in \mathbf{C}$ )? Use again the definition.

*Hint:* Write this complex equation as a 2-dimensional real system by introducing the real and imaginary parts of  $z$ , i.e. by setting  $z = x + iy$  and deriving equations for  $\dot{x}$  and  $\dot{y}$ . Make a sketch of the phase portrait. Note that *instability* is defined as *not* being stable (page 116 book).

- 2.) Consider the linear system,

$$\begin{cases} \dot{x} &= Ax + B(t)x, \quad x \in \mathbf{R}^n, n \geq 1, \\ x(0) &= x_0, \end{cases} \quad (1)$$

with  $A$  a  $n \times n$  matrix (with constant coefficients) and  $B(t)$  a  $n \times n$  matrix with coefficients that depend continuously on time  $t$ ; define  $\phi(t; x_0)$  as the solution of (1). Moreover, it is given that there is a (positive) continuous function  $C : \mathbf{R}^+ \rightarrow \mathbf{R}^+$  such that  $\|B(t)x\| < C(t)\|x\|$  for all  $x \in \mathbf{R}^n$  and  $t \geq 0$ .

(*Note:* For given  $B(t)$ , functions  $C(t)$  like defined here always exist; the infimum over all possible  $C(t)$ 's defines the norm  $\|B(t)\|$  of the matrix  $B(t)$ .)

- (a) Explain why  $\tilde{\phi}(t; x_0) = e^{At + \int_0^t B(s)ds} x_0$  is, in general, not a solution of (1).

Assume first that,

- ( *Ai* ) all eigenvalues  $\lambda_j$  of  $A$  satisfy  $\operatorname{Re} \lambda_j < 0$ ;  
( *Bi* )  $\lim_{t \rightarrow \infty} C(t) = 0$ .

- (b) Show that it follows from assumptions ( *Ai* ) and ( *Bi* ) that  $\lim_{t \rightarrow \infty} \phi(t; x_0) \rightarrow 0$  for all  $x_0 \in \mathbf{R}^n$  and that the critical point  $x^* = 0$  of (1) is asymptotically stable (use the definition!).

*Hint.* Apply the arguments of the proof of Theorem 4.6 (in the book) with  $g(y)$  replaced by  $B(t)x$ .

Now assume that,

- ( *Aii* ) all eigenvalues  $\lambda_j$  of  $A$  satisfy  $\operatorname{Re} \lambda_j \leq 0$ ;  
( *Aiii* ) the eigenvalues  $\lambda_j$  of  $A$  with  $\operatorname{Re}(\lambda_j) = 0$  do not coincide (i.e. these eigenvalues have – algebraic and geometric – multiplicity 1);  
( *Bii* )  $C(t)$  is integrable:  $\int_0^\infty C(t) dt = D < \infty$ .

In the subsequent exercises it may be used that for matrices  $A$  that satisfy assumptions ( *Aii* ) and ( *Aiii* ), there is a  $K > 0$  such that  $|e^{At}x_0| < K|x_0|$  for all  $x_0 \in \mathbf{R}^n$  and  $t \geq 0$ .

- (c) Show that it follows from assumptions (Aii), (Aiii), and (Bii) that the critical point  $x^* = 0$  of (1) is stable. Use the definition.
- (d) Assumption (Bii) is (only slightly) stronger than (Bi). Does the statement of (c) also hold if (Bii) replaced by (Bi)? If yes: give a proof; if no: give a counterexample.
- (e) Is additional assumption (Aiii) really necessary for the proof of (c)? Explain!

3.) Consider the  $n$ -dimensional system

$$\dot{X} = AX + F(X), \quad (2)$$

with  $A$  an  $n \times n$  constant coefficients matrix and  $F(X)$  a nonlinear expression that satisfies  $\|F(X)\| \leq C\|X\|^2$  as  $\|X\| \rightarrow 0$ , for some  $C > 0$ . Recall that we cannot draw any conclusions on the stability of the critical point  $\bar{X} = 0$  of (2) if  $A$  has eigenvalues  $\lambda$  with  $\text{Re}(\lambda) = 0$ . Take  $n = 2$ ,  $A = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$ , and write  $X$  as  $(x, y)$ . Show that the critical point  $\bar{X} = (\bar{x}, \bar{y}) = (0, 0)$  of (2) is

(a) unstable for  $F(X) \equiv 0$ .

(b) stable for  $F(X) = F(x, y) = \begin{pmatrix} 0 \\ -x^3 \end{pmatrix}$ .

*Hint:* Write (2) as equation in  $\ddot{x}$  and determine a *first integral*  $V(x, y)$  of this equation, i.e. a function  $V(x, y)$  such that  $\frac{d}{dt}V(x, y) = 0$  for solutions of the equation. Use this  $V(x, y)$  as Lyapunov function.

(c) asymptotically stable for  $F(X) = F(x, y) = \begin{pmatrix} -x^3 \\ -x^3 - y^3 \end{pmatrix}$ .

*Hint:* Use the Lyapunov function constructed in (b).

(d) Keep  $n$  and  $A$  as above and consider  $F(x, y) = \begin{pmatrix} 0 \\ \alpha x^\ell \end{pmatrix}$  for  $\alpha \in \mathbf{R}$  and  $\ell = 2, 3, 4, \dots$ . What can you say about the stability of  $(0, 0)$  as function of  $\alpha$  and  $\ell$ ?

(e) Now consider  $F(x, y) = \begin{pmatrix} f(x) \\ g(x) \end{pmatrix}$  with nonlinearities  $f, g : \mathbf{R} \rightarrow \mathbf{R}$  smooth analytic functions of  $x$  such that the limits  $\lim_{x \rightarrow 0} \frac{f(x)}{x^k}$  and  $\lim_{x \rightarrow 0} \frac{g(x)}{x^\ell}$  both exist and are  $\neq 0$  for some  $k, \ell \geq 2$ . Keep  $n$  and  $A$  still as above. Determine necessary and sufficient conditions on  $f$  and  $g$  so that  $(0, 0)$  is stable/asymptotically stable.