Madrid - July 9th 2014

Travelling Waves for Fully Discretized Bistable Reaction-Diffusion Problems

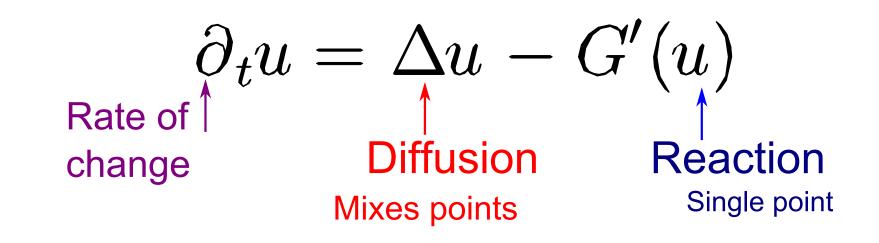


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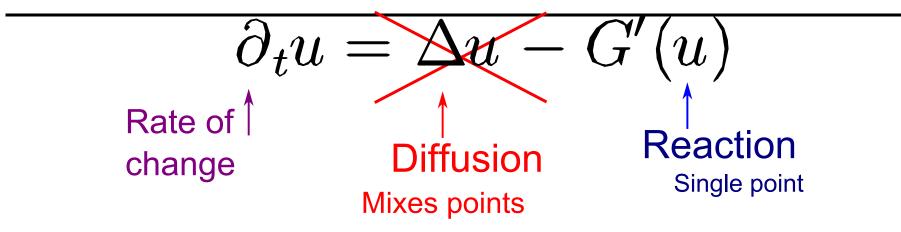
(Joint work with Erik van Vleck - U. Kansas)

Reaction-Diffusion System

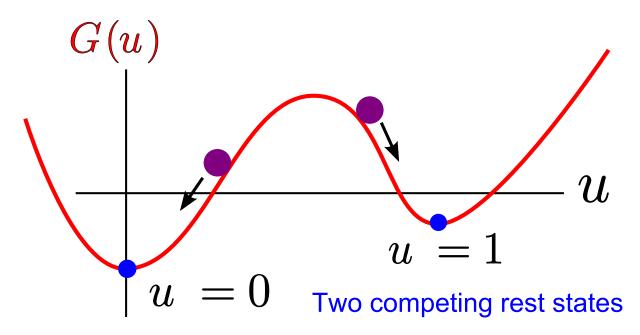


- **Continuous** spatial variable: $x \in \mathbb{R}$.
- **Continuous** temporal variable: $t \in \mathbb{R}$.
- $0 \le u(x,t) \le 1$
- Prototype for **Pattern formation**.

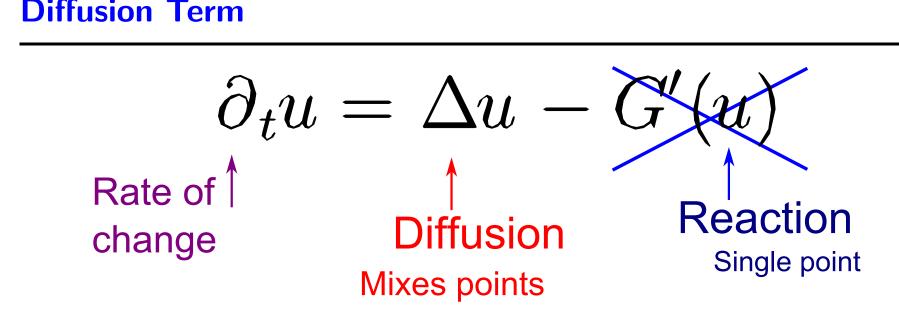
Reaction Term



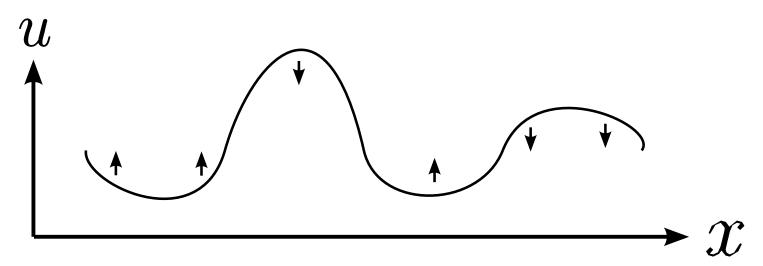
- Think of G(u) as a potential.
- Ignoring spatial variations, u moves through potential landscape.



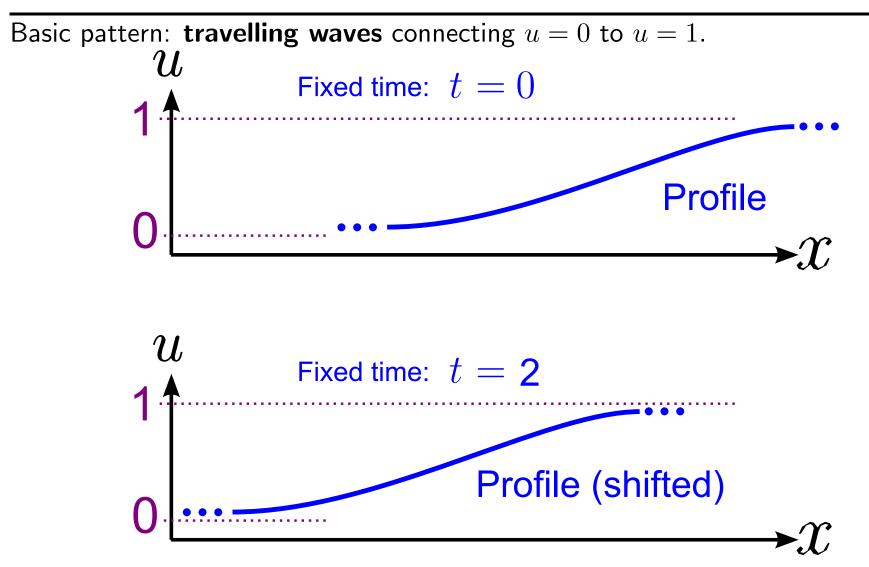
Diffusion Term



• Diffusion: flattens wrinkles.



Travelling Waves

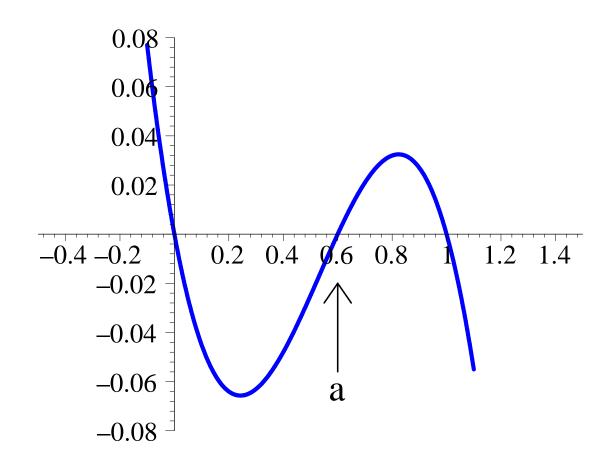


• Building blocks for more complex patterns.

Nonlinearity

For concreteness, will use quartic potential; i.e.

$$-G'(u) = -G'(u; a) = g_{\rm cub}(u; a) = u(1-u)(u-a)$$



Travelling wave: PDE

Nagumo PDE with $g_{cub}(\cdot; a)$:

$$\partial_t u = \partial_{xx} u + u(1-u)(u-a).$$

Starting step [Fife, McLeod]: travelling waves.

Travelling wave $u(x,t) = \Phi(x+ct)$ satisfies:

$$c\Phi'(\xi) = \Phi''(\xi) + \Phi(\xi) (1 - \Phi(\xi)) (\Phi(\xi) - a).$$

Interested in pulse solutions connecting 0 to 1, i.e.

$$\lim_{\xi \to -\infty} \Phi(\xi) = 0, \qquad \lim_{\xi \to +\infty} \Phi(\xi) = 1.$$

Signal Propagation: PDE

Recall travelling wave ODE

$$c\Phi'(\xi) \qquad = \quad \Phi''(\xi) + \Phi(\xi) \big(a - \Phi(\xi) \big) \big(\Phi(\xi) - 1 \big).$$

$$\lim_{\xi \to -\infty} \phi(\xi) = 0,$$
$$\lim_{\xi \to +\infty} \phi(\xi) = 1.$$

Explicit solutions available:

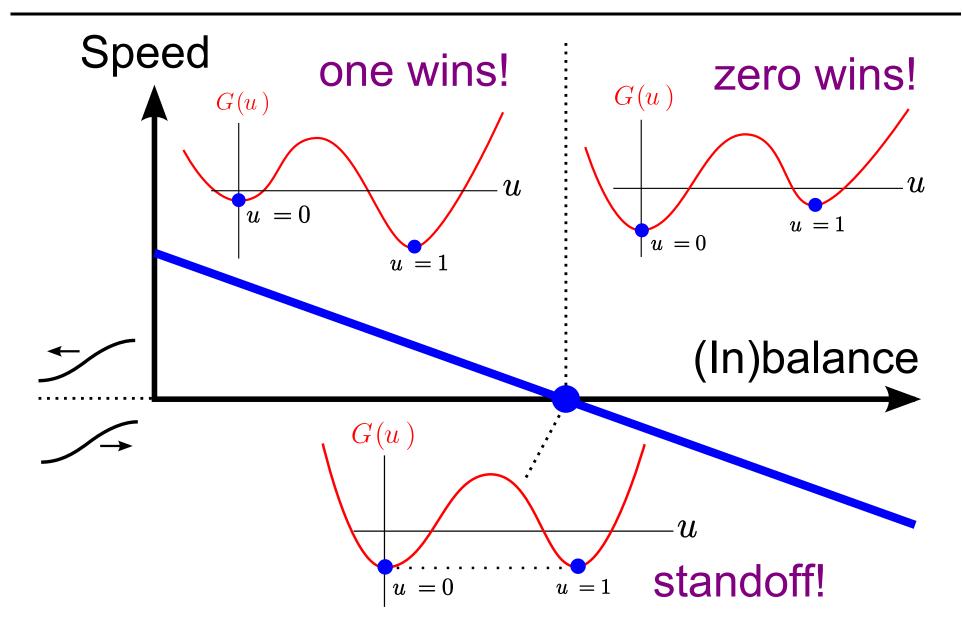
$$\Phi(\xi) = \frac{1}{2} + \frac{1}{2} \tanh\left(\frac{1}{4}\sqrt{2}\,\xi\right), \\ c(a) = \frac{1}{\sqrt{2}}(1-2a).$$

$$C$$

$$c = \frac{1}{2}\sqrt{2}$$

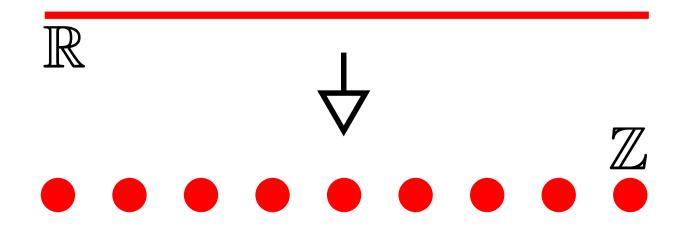
$$a = \frac{1}{2}$$

Continuous space



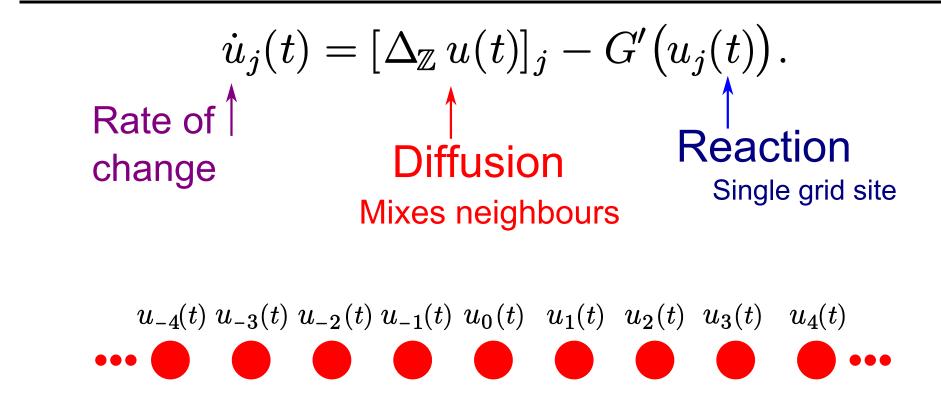
Step 1 - Spatial Discretization

• Translational symmetry broken



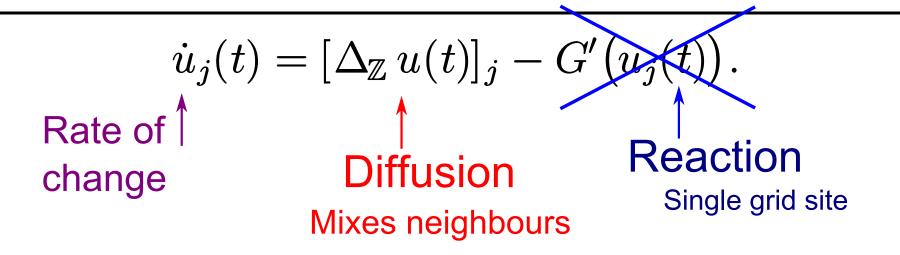
- Gaps in discrete space: barriers
- Fundamental difference between Moving Waves and Standing Waves

Reaction-Diffusion System

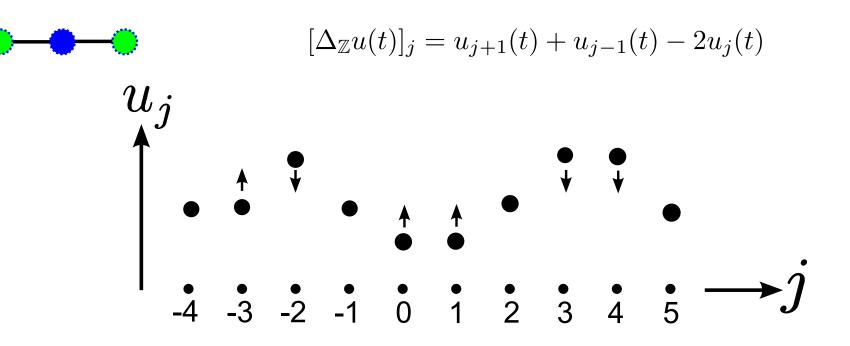


- **Discrete** spatial variable: $j \in \mathbb{Z}$.
- **Continuous** temporal variable: $t \in \mathbb{R}$.
- $0 \le u_j(t) \le 1$

Diffusion Term

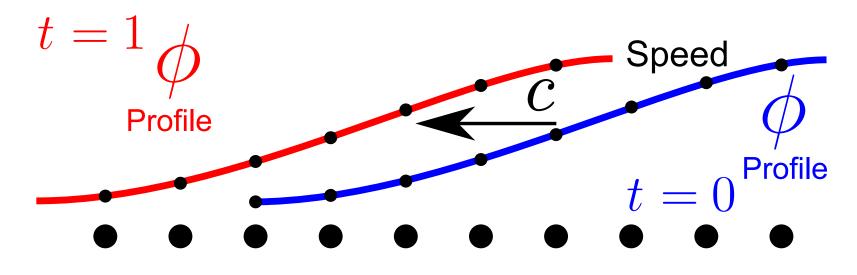


• Diffusion: flattens variations between neighbours.



Travelling Waves

Again: Basic pattern: travelling waves connecting u = 0 to u = 1.



Different times see different **discrete samples** of **smooth** underlying profile.

Consider the Nagumo LDE

$$\frac{d}{dt}u_j(t) = [u_{j+1}(t) + u_{j-1}(t) - 2u_j(t)] + g_{\rm cub}(u_j(t);a), \qquad j \in \mathbb{Z}.$$

Travelling wave profile $u_j(t) = \Phi(j + ct)$ must satisfy:

$$c\Phi'(\xi) = \Phi(\xi+1) + \Phi(\xi-1) - 2\Phi(\xi) + g_{cub}(\Phi(\xi);a)$$

$$\lim_{\xi \to -\infty} \Phi(\xi) = 0,$$
$$\lim_{\xi \to +\infty} \Phi(\xi) = 1.$$

- Notice that wave speed c enters in singular fashion.
- When $c \neq 0$, this is a functional differential equation of mixed type (MFDE).
- When c = 0, this is a difference equation.

Propagation Failure

Recall travelling wave MFDE:

$$c\Phi'(\xi) = [\Phi(\xi+1) + \Phi(\xi-1) - 2\Phi(\xi)] + g_{\rm cub}(\Phi(\xi);a)$$

$$\lim_{\xi \to -\infty} \phi(\xi) = 0,$$
$$\lim_{\xi \to +\infty} \phi(\xi) = 1.$$

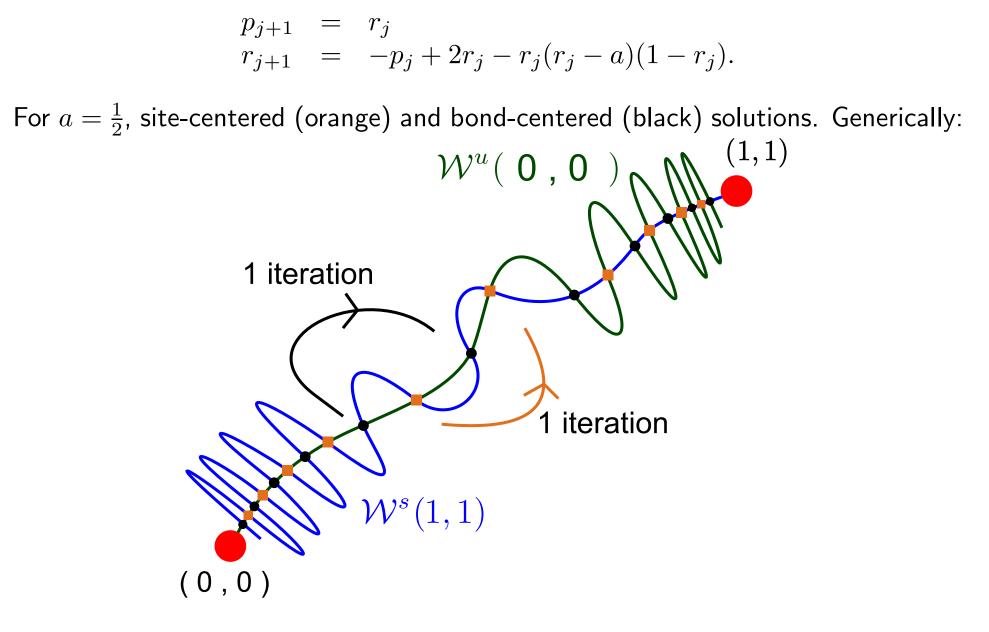
When c = 0, can restrict to $\xi \in \mathbb{Z}$: recurrence relation!

With $p_j = \Phi(j)$ and $r_j = \Phi(j+1)$, we find

$$p_{j+1} = r_j$$

 $r_{j+1} = -p_j + 2r_j - r_j(r_j - a)(1 - r_j).$

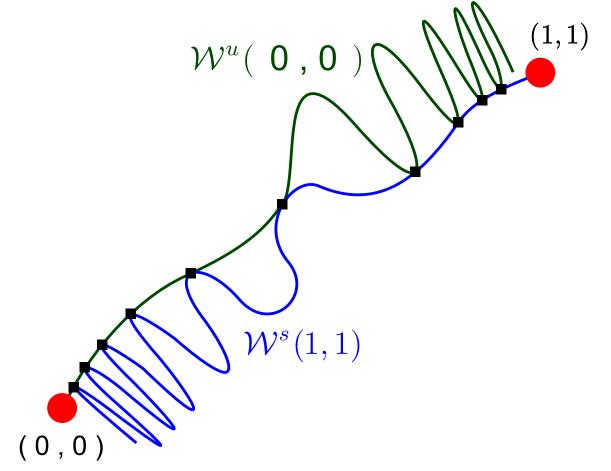
Saddles (0,0) and (1,1).



$$p_{j+1} = r_j$$

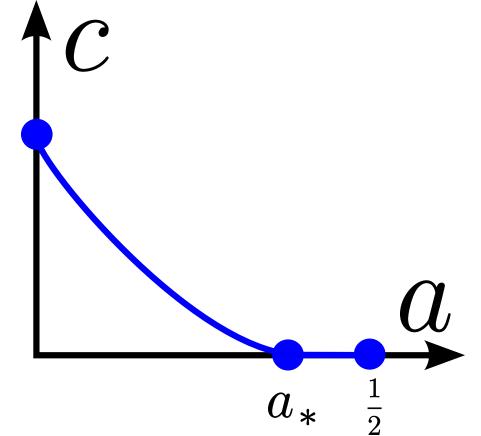
$$r_{j+1} = -p_j + 2r_j - r_j(r_j - a)(1 - r_j).$$

Two branches coincide and annihilate at $a = a_*$.



Propagation

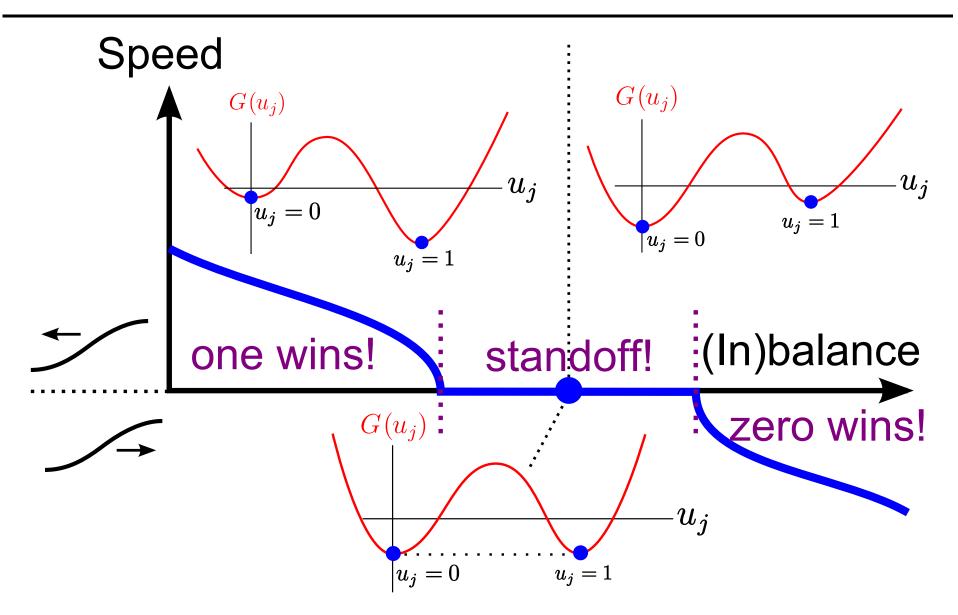
Typical wave speed c versus a plot for discrete reaction-diffusion systems:



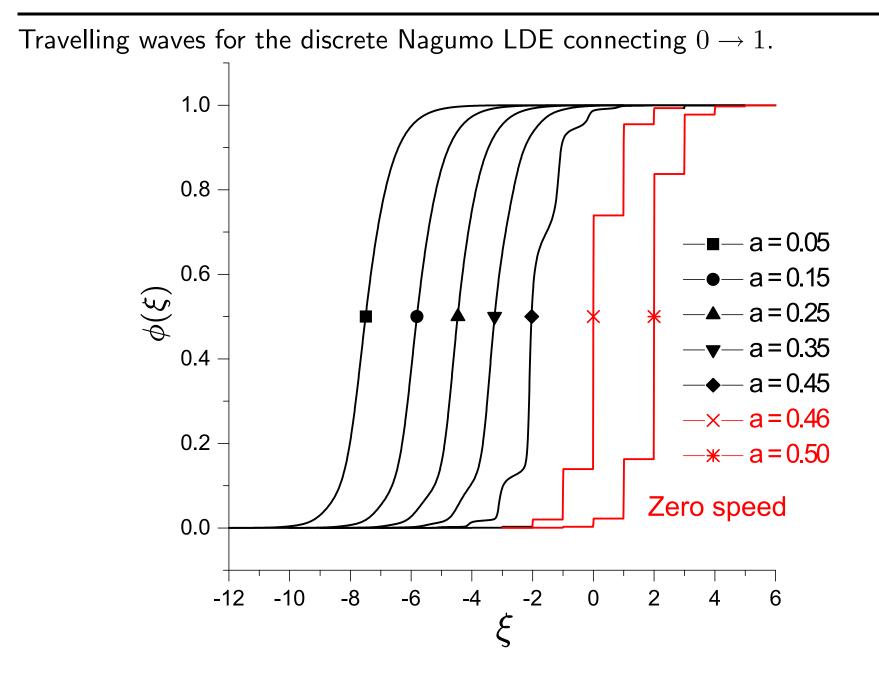
Wave speed c depends **uniquely** on a.

In case $a_* < \frac{1}{2}$, then we say that LDE suffers from propagation failure. Propagation failure common for LDEs [Keener, Mallet-Paret, Hoffman, ...].

Discrete space



Discrete Nagumo LDE - Propagation failure



Step Two - Temporal Discretization

Apply Backward-Euler time discretization with time-step Δt :

$$\frac{1}{\Delta t} \left[u_j(t) - u_j(t - \Delta t) \right] = \left[\Delta_{\mathbb{Z}} u(t) \right]_j - G'(u_j(t)).$$

- Temporal variable t now in $(\Delta t)\mathbb{Z}$ (discrete).
- Spatial variable $j \in \mathbb{Z}$ still discrete.

Travelling wave Ansatz $u_j(t) = \Phi(j + ct)$ now yields

$$c[\mathcal{D}_{1,M}\Phi](\zeta) = \Phi(\zeta+1) + \Phi(\zeta-1) - 2\Phi(\zeta) - G'(\Phi(\zeta))$$

in which $M = (c\Delta t)^{-1}$ and

$$[\mathcal{D}_{1,M}\Phi](\zeta) = M[\Phi(\zeta) - \Phi(\zeta - M^{-1})]$$

Domain of ζ depends on M. Dense in \mathbb{R} if M irrational; otherwise periodic.

BDF Methods

- Backward-Euler discretization is the order k = 1 BDF (Backward Differentiation Formula) method.
- These methods are L-stable (slightly worse than A-stable); much better than forward Euler.
- Methods available up to order k = 6.

With BDF order k discretization, wave must solve:

$$c[\mathcal{D}_{k,M}\Phi](\zeta) = \Phi(\zeta+1) + \Phi(\zeta-1) - 2\Phi(\zeta) - G'(\Phi(\zeta)).$$

Example for k = 2:

$$[\mathcal{D}_{2,M}\Phi](\zeta) = \frac{3}{2}M\Big[\Phi(\zeta) - \frac{4}{3}\Phi(\zeta - M^{-1}) + \frac{1}{3}\Phi(\zeta - 2M^{-1})\Big]$$

For smooth functions ϕ :

$$\left[\mathcal{D}_{k,M}\phi - \phi'\right](\zeta) = O(M^{-k} \left\|\phi^{(k+1)}\right\|_{\infty}).$$

Backward-Euler: restatement

For backward-Euler one can look for solutions to

$$\tilde{c}\Phi'(\xi) = \frac{1}{\Delta t} [\Phi(\xi - c\Delta t) - \Phi(\xi)] + \Phi(\xi + 1) + \Phi(\xi - 1) - 2\Phi(\xi) - G'(\Phi(\xi); a)$$

with $\widetilde{c} = 0$.

All shifted terms have **positive** coefficients. Allows framework of Mallet-Paret for **spatial discretization** to be applied for **fixed** c and Δt .

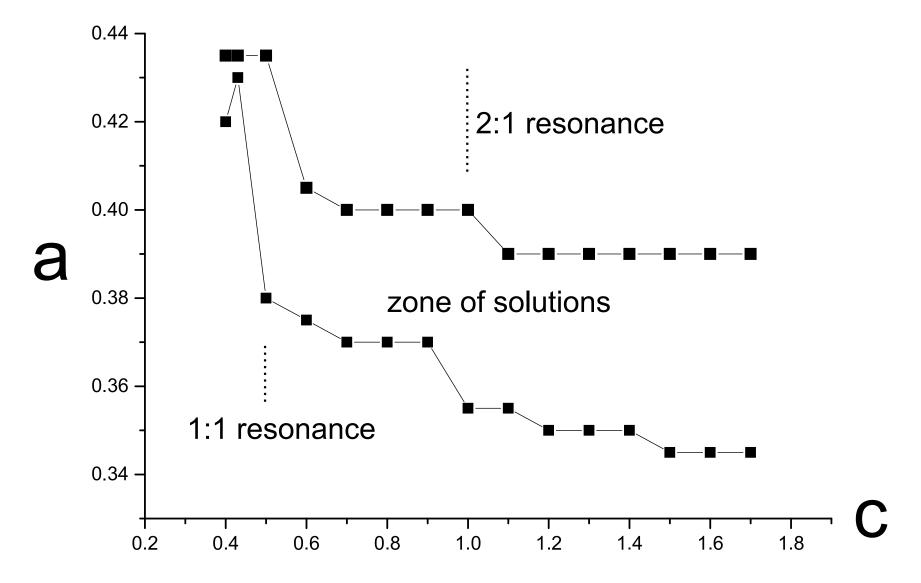
This gives unique $\tilde{c} = \tilde{c}(c, a)$.

Thm. [H., Van Vleck based on Mallet-Paret] Fix Δt . For all c sufficiently small, there is at least one a for which $\tilde{c}(c, a) = 0$.

Numerical insights Generically, $\tilde{c}(c, a) = 0$ for range of a [propagation failure]. Wave speed c is no longer a unique function of a. [Critical intervals $[a_{-}(c), a_{+}(c)]$ overlap for different values of c]

Backward-Euler: non-uniqueness of wave speed

Regions in (c, a) space where solutions exist.



Singular perturbation

For orders $2, 3, \ldots 6$, this monotonic structure is not available.

Goal here is to fix a and look at $cT \rightarrow 0$, writing

$$\Phi(\zeta) = \Phi_*(\zeta) + v(\zeta), \qquad c = c_* + c'$$

where (c_*, Φ_*) is the wave for the **spatially discrete** problem.

However the bifurcation is singular, in the sense that one must solve

$$\mathcal{L}_{k,M}v = O(v^2 + M^{-1} + c'),$$

with

$$[\mathcal{L}_{k,M}v](\zeta) = -c_*\mathcal{D}_{k,M}v + v(\zeta+1) + v(\zeta-1) - 2v(\zeta) + g'(\Phi_*(\zeta))v(\zeta).$$

We only know that

$$[\mathcal{L}_*v](\xi) = -c_*v'(\xi) + v(\xi+1) + v(\xi-1) - 2v(\xi) + g'(\Phi_*(\xi))v(\xi).$$

is Fredholm with index zero as $H^1 \to L^2$ map, with $\operatorname{Ker} \mathcal{L}_* = \{\Phi_*\}$. Can we lift?

Spectral convergence

- Comparison between $\mathcal{L}_{k,M}$ and \mathcal{L}_* can be studied based by adapting 'spectral convergence' technique [Bates, Chen, Chmaj].
- Compares **resolvents** of linear operators \mathcal{A} and \mathcal{A}_M assuming that $\sigma(\mathcal{A}_M) \to \sigma(\mathcal{A})$ as $M \to \infty$ on compact subsets of \mathbb{C} .
- Step A: use weak convergence to pass to a weak limit.
- Step B: recover 'missing' information by exploiting equation.

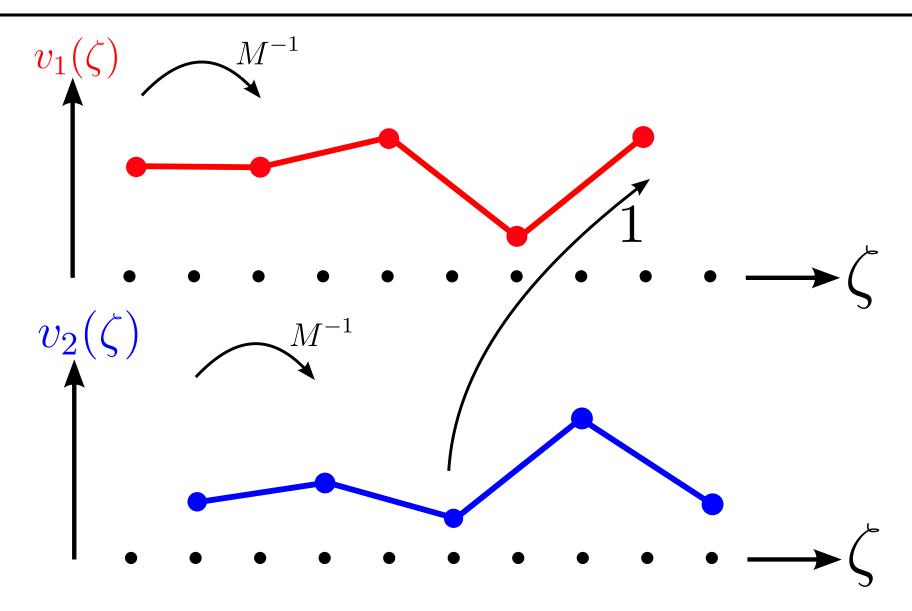
Step A: Weak Convergence

Need to build an H^1 -function from sequence $v(\zeta) \qquad \qquad M^{-1} \qquad \qquad 1$

Here $M = \frac{3}{2}$ so $\zeta \in \frac{1}{3}\mathbb{Z}$.

Cannot directly do interpolation in a **controlled** fashion.

Step A: Weak Convergence



After splitting; can interpolate. Size of derivative controlled by $\mathcal{D}_{k,M}v$.

Step B: Missing information

- Bounded sequence of H^1 functions converge (after subsequence) weakly in H^1 and **strongly** on $L^2([a, b])$.
- Weak limit V satisfies limiting problem $\mathcal{L}_*V = 0$.
- Task: rule out V = 0.
- Here exploit **bistable** nature of equation plus monotonic structure of discrete Laplacian
- Can show that $\mathcal{D}_{k,M}v$ can not get too big as $M \to \infty$
- This gives lower bound on $L^2([a,b])$ norm of limit V.

The result

Looking for travelling wave (c, v) of form

$$\Phi(\zeta) = \Phi_*(\vartheta + \zeta) + v(\zeta)$$

to system

$$c\mathcal{D}_{k,M}\Phi = \Phi(\zeta+1) + \Phi(\zeta-1) - 2\Phi(\zeta) + g_{\text{cub}}(\Phi(\zeta);a)$$

Thm. [H., Van Vleck] Fix integer $q_* > 1$. There exists $M_* \gg 1$ so that for all $M \ge M_*$ and $M = \frac{p}{q}$ with $q \le q_*$ there are unique solutions $c_M(a, \vartheta)$ and $v_M(a, \vartheta)$.

- Δt can be recovered via $M^{-1} = c\Delta t$
- Speed $c_M(a, \vartheta) = c_* + O(M^{-1})$
- Periodicity $c_M(a, \vartheta + M^{-1}) = c_M(a, \vartheta)$.
- Monotonicity $\partial_a c_M(a, \vartheta) < 0$.

We have **non-uniqueness** of wave speed c as a function of a and a as a function of c provided we can show that $\partial_{\vartheta}c_M(a,\vartheta) \neq 0$. But this is $O(e^{M^{-1}})$.